

Mobile scanning for the real world - continuous realtime registration and rendering for indoor and outdoor environments

SurphSLAM 10

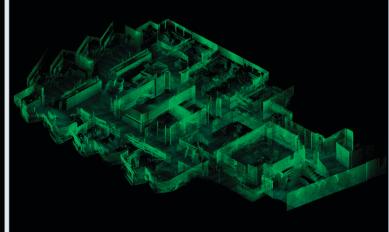
- Based on Surphaser 3D laser scanner model 10 and GeoSLAM RealTime Software
- Works anywhere seamlessly transition between indoors and outdoors, on uneven and sloping terrain
- Realtime feedback see the map being built as you walk, see your path and plan where you need to go
- Instant results review and download the fully registered point cloud after every scan



Street scene: distance 521.99 m, scanning and registration time 9.1 mins



Office: distance 283.70m, scanning and registration time 7.7 mins



Points: 24,437,438

Bounding box:

length: 187.30m, xmin: -91.65m, xmax: 95.65m width: 45.73m, ymin: -16.31m, ymax: 29.41m height: 3.21m, zmin: -3.15m, zmax: 0.06m

Average speed 0.96m/s

Points: 21,130,810

Bounding box:

length: 27.22m, xmin: -1.35m, xmax: 25.87m width:19.69m, ymin: -1.18m, ymax: 18.51m height: 0.06m, zmin: 0.02m, zmax: 0.08m

Average speed 0.61m/s

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System Specification

Laser Sensor

Surphaser Model 10

Range measurement Phase shift

Laser Wavelength 1550nm

Laser TypeCWLaser ClassClass 1Maximum Range130m

Angular FOV 270° x 360°

Data Acquisition Rate 208,000 points/sec

Operating Parameters

Scanner Mirror Speed 90Hz

Scanner Lateral Density 2° azimuth @0.5Hz azimuth

6 points/deg vertical

Recommended maximum speed 1m/s

Azimuth Rotation Speed 0.1-0.5Hz

Operating Temperature 5°C to +40°C

Physical Parameters

Weight 17.5kg

Scanner 5.0kg Trolley 8.0kg

Battery pack 4.5kg

Dimensions L x W x H 80cm x 50cm x 120cm

User Interface

Interface screen Any device with WiFi and

WebGL-enabled web

browser

Power consumption

Scanner 30W 14-19VDC

Processing Unit 55W

Power supply

Battery Type Lithium Ion
Battery Capacity 90Wh each

No. batteries 4
Hot swappable Ye

Hot swappable Yes

Battery Life 4 hours (continuous use)

Charge Time 2 hours (using provided

250W DC supply)

Data

Data Storage Capacity 350GB

Raw data file size ~100MB for every 1 min

scanning

Processed data file size ~10MB-20MB for every 1

min scanning

Default output file format .LAZ (compressed .LAS)

Accuracy

Local Accuracy, better than 1cm

Absolute Position Accuracy* 1 – 5cm

(10 mins scanning,

1 loop)

^{*} Expected accuracy range in feature rich environment.